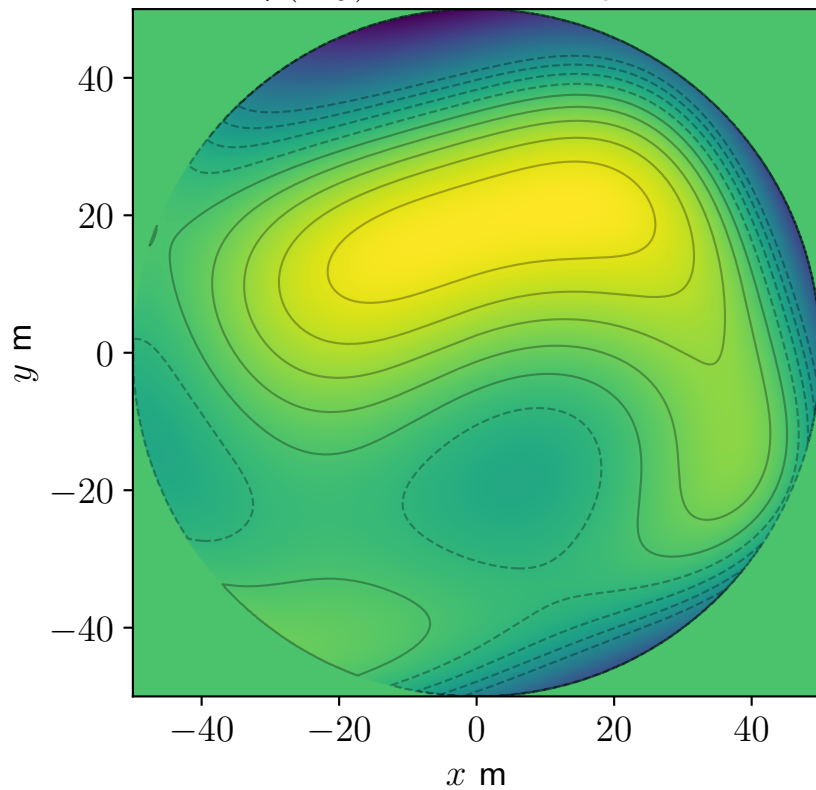


$\varphi(x, y)$ no-tilt and no-piston



$\varphi(x, y)$

